# A geometrical version of the higher order Hamilton formalism in fibred manifolds 

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#### Abstract

It has been clarified recently that an $r$-th order Lagrangian on a fibred manifold $Y \rightarrow X$ does not determine a unique Poincaré-Cartan form provided $\operatorname{dim} X>1$ and $r>2$, [1], [4], [6], [9], [10]. To make this fact more transparent, we introduced a new operation generalizing the formal exterior differentiation, [6]. In the present paper we deduce in such a way that a unique Poincaré-Cartan form can be determined by means of a simple additional structure - a linear symmetric connection $\Gamma$ on the base manifold $X$ (or, more generally, by a convenient splitting S). Then we present a suitable geometric definition of a regular $r$-th order Lagrangian on $Y$ and we prove that any our Poincaré-Cartan form can be used in a geometrical version of the higher order Hamilton formalism.


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## 1. DECOMPOSITION FORMULA

All manifolds and maps are assumed to be infinitely differentiable and all morphisms of fibred manifolds are base-preserving. - Given a fibred manifold $\pi: Y \rightarrow X$, we denote by $\pi_{r}: J^{r} Y \rightarrow X$ its $r$-th jet prolongation and by $\pi_{r}^{s}: J^{r} Y \rightarrow J^{s} Y, 0 \leqslant s \leqslant r,\left(J^{0} Y=Y\right)$ the jet projections. If $x^{i}, y^{p}, i, j, \ldots=1$,

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$\ldots n=\operatorname{dim} X, p, 4-1 \ldots m=\operatorname{dim} Y-\operatorname{dim} X$. are some local fibre coordinates on $Y$, then the induced coordinates on $J^{r} Y$ are $x^{i},{ }_{3}^{\prime P}$ for all multimdices $|\alpha| \leqslant r$. As usual, $\alpha+\beta$ means the sum of two multiindices, $(\alpha+\beta)_{i}=\alpha_{i}+\beta_{i}$ Any ordinary index $i$ can be interpreted as a multiindex with $i$-th component 1 and all other components 0 . Since we have to discuss some problems of tensorial character. we shall also use the classical notation of the tensor calculus. In such a situation we write $y_{\alpha}^{p}=y_{j_{1} \ldots j_{k}}^{p}$ for $\alpha=j_{1}+\ldots+j_{k}$. We use the summation convention for ordinary indices, but we always indicate explicitely the summation with respect to multiindices. We set $\omega=\mathrm{d} x^{1} \wedge \ldots \wedge \mathrm{~d} x^{n}, \omega_{i}=\frac{\partial}{\partial x^{i}}-\perp \omega$.

For every morphism $\varphi: J^{r} Y \rightarrow \Lambda^{k} T^{*} X$, one defines its formal exterior differential $D \varphi: J^{r+1} Y \rightarrow \wedge^{k+1} T^{*} X$ by $\left(j^{r+1} s\right)^{*} D \varphi=\mathrm{d}\left(\left(j^{r} s\right)^{*} \varphi\right)$ for every local section $s$ of $Y$. [13]. If the local coordinate expression of $\varphi$ is $\varphi=a_{i_{1} \ldots i_{k}}\left(x^{i}, y_{\alpha}^{p}\right) \mathrm{d} x^{i_{1}} \wedge$ $\wedge \mathrm{d} x^{i_{k}}$, then $D_{\varphi}=D_{j} a_{i_{1} \ldots i_{k}} \mathrm{~d} x^{j} \wedge \mathrm{~d} x^{i_{1}} \wedge \ldots \wedge \mathrm{~d} x^{i_{k}}$. where $D_{j} f=\partial_{j} f+$ $\sum_{a}\left(\partial_{p}^{a} f\right) y_{a+j}^{p}, \partial_{j}=\partial / \partial x_{j}, \partial_{p}^{\alpha}=\partial / \partial y_{a}^{p}$, denotes the formal (or total) derivative of a function $f: J^{r} Y \rightarrow \mathbf{R}$. Clearly. $D D \varphi=0$. Any vertical vector field $\eta$ on $\gamma$ induces a vector field $J^{r} \eta$ on $J^{r} Y$ such that $\exp \left(t J^{r} \eta\right)=J^{r}(\exp t \eta)$, where $\exp t \xi$ means the flow of a vector field $\xi$. In coordinates. if $\eta=\eta^{p}\left(x, \ldots \dot{d}_{p}\right.$. then $J^{r} \eta=\sum_{\mid \alpha \leqslant r}\left(D_{a} \eta^{p}\right) \partial_{p}^{\alpha}$. This implies directly: for every morphism $A: J^{r} Y^{r} \rightarrow$ $I^{*} J^{s} Y \otimes \wedge^{k} T^{*} X$ over the identity of $J^{s} Y, s \leqslant r$. there exists a unique morphism $\mathscr{D} A: J^{r+1} Y \rightarrow V^{*} J^{s+1} Y \otimes \bigwedge^{k+1} T^{*} X$ satisfying

$$
\begin{equation*}
\left\langle\mathscr{D} A, J^{s+1} \eta\right\rangle=D\left\langle A, J^{s} \eta\right\rangle \tag{1}
\end{equation*}
$$

for every vertical vector field $\eta$ on $Y$. [6]. Obviously, $\mathscr{D} \mathscr{D} A=0$. For $k=n-1$ we write $A=\sum_{|\alpha| \leqslant s} a_{p}^{\alpha i} \mathrm{~d}_{a}^{p} \otimes \omega_{i}$, where $\alpha i$ is a pair of a multiindex and an ordinary index, and we have

$$
\begin{equation*}
\mathscr{D} A=\sum_{i \alpha \mid \leqslant s}\left[\left(D_{i} a_{p}^{\alpha i}\right) \mathrm{d}_{a}^{p}+a_{p}^{\alpha i} \mathrm{~d} y_{a+i}^{p}\right] \otimes \omega \tag{2}
\end{equation*}
$$

We define an $r$-th order Lagrangian on $Y$ as a morphism $\left.\lambda: J^{r} Y \rightarrow \Lambda^{n} T^{*}.\right\}$. $\lambda=L\left(x^{i}, y_{\alpha}^{p}\right) \omega,[13]$. Its vertical differential $\delta \lambda=\underset{\text { a }}{\Sigma_{r}}\left(\partial_{p}^{\alpha} L\right) d_{\alpha}^{p} \otimes \omega$ can bc interpreted as a map $J^{r} Y \rightarrow V^{*} J^{r} Y \otimes \wedge^{n} T^{*} X$. For the tensorial considerations we introduce

$$
\begin{equation*}
L_{p}^{j_{1} \cdots j_{k}}=\frac{\alpha!}{k!} \partial_{p}^{\alpha} L \quad \text { for } \quad \alpha=j_{1}+\ldots+j_{k} \tag{3}
\end{equation*}
$$

Then we have

$$
\begin{equation*}
\delta \lambda=\left(L_{p} \mathrm{~d} y^{p}+\ldots+L_{p}^{j_{1} \cdots j_{r}} \mathrm{dy}_{j_{1} \cdots j_{r}}^{p}\right) \otimes \omega . \tag{4}
\end{equation*}
$$

We clarified in [6] and [9] that a basic problem is to discuss a decomposition

$$
\begin{equation*}
\delta \lambda=\mathscr{D} M+E \tag{5}
\end{equation*}
$$

with $M: J^{2 r-1} Y \rightarrow V^{*} J^{r-1} Y \otimes \wedge^{n-1} T^{*} X$ and $E: J^{2 r} Y \rightarrow V^{*} Y \otimes \wedge^{n} T^{*} X$ (the injection $V^{*} Y \rightarrow V^{*} J^{r} Y$ being tacitly used here).

Write $M=\sum_{\alpha \mid \leqslant r \cdots 1} b_{p}^{\alpha i} \mathrm{~d} y_{\alpha}^{p} \otimes \omega_{i}$. Similarly to (3), we set $B_{p}^{j_{1} \cdots j_{k} i}=\frac{\alpha!}{k!} b_{p}^{\alpha i}$, $\alpha=j_{1}+\ldots+j_{k}$, so that $B ' s$ are symmetric in $j_{1}, \ldots, j_{k}$, not in $i$. Then

$$
\begin{equation*}
M=\left(B_{p}^{i} \mathrm{~d} y^{p}+\ldots+B_{p}^{j_{1} \ldots j_{r-1} i} \mathrm{~d}_{j_{1} \ldots j_{r-1}}^{p}\right) \otimes \omega_{i} \tag{6}
\end{equation*}
$$

Decomposition (5) leads to the following equations

$$
\begin{align*}
L_{p}^{j_{1} \cdots j_{r}} & =B_{p}^{\left(j_{1} \cdots j_{r}\right)} \\
& \vdots  \tag{7}\\
L_{p}^{j_{1} \cdots j_{k}} & =D_{i} B_{p}^{j_{1} \cdots j_{k} i}+B_{p}^{\left(j_{1} \cdots j_{k}\right)} \\
& \vdots \\
L_{p} & =D_{i} B_{p}^{i}+\mathrm{e}_{p}
\end{align*}
$$

with $E=\mathrm{e}_{p} \mathrm{~d} y^{p} \otimes \omega$.
Evaluating $e_{p}$ by a backward procedure, we find for any $B^{\prime} s$

$$
\begin{equation*}
e_{p}=\sum_{|\alpha| \leqslant r}(-1)^{|\alpha|} D_{a} \partial_{p}^{\alpha} L \tag{8}
\end{equation*}
$$

so that the Euler morphism $E$ is uniquely determined. On the other hand, $M$ cannot be unique in general: if we take any $C: J^{2 r-2} Y \rightarrow V^{*} J^{r-2} Y \otimes \wedge^{n-2} T^{*} X$, then $M+\mathscr{D} C$ also satisfies (5) by virtue of $\mathscr{D} \mathscr{D} C=0$. In [9]. we proved the global existence of such a morphism $M$ and we also deduced a converse assertion: if $M$ and $\bar{M}$ are two morphisms satisfying (5), then there exists a morphism $C: J^{2 r-2} Y \rightarrow V^{*} J^{r-2} Y \otimes \wedge^{n}{ }^{2} T^{*} X$ such that $\bar{M}=M+\mathscr{D} C$. In particular, $M$ is unique for $r=1$ and any $n$ or $n=1$ and any $r$.

Define a vector bundle $K_{r-1}^{s}$ over $J^{r-1} Y$ by an exact sequence

$$
\begin{equation*}
0 \rightarrow K_{r-1}^{s} \rightarrow V J^{r-1} Y \xrightarrow{V \pi_{r-1}^{s}}\left(\pi_{r-1}^{s}\right)^{!} V^{*} J^{s} Y \rightarrow 0 \tag{9}
\end{equation*}
$$

where $\left(\pi_{r-1}^{s}\right)^{\prime}$ denotes the pullback over $J^{r-1} Y$. For $s=r-2$, the fibers of $K_{r-1}^{r-2}$ are $V Y \otimes S^{r-1} T^{*} X$. If we compose the dual map $V^{*} J^{r-1} Y \rightarrow K_{r}^{r-2_{1}^{*}}$ with $M$. we obtain $\tilde{M}: J^{2 r}{ }^{1} Y \rightarrow V^{*} Y \otimes S^{r}{ }^{1} T X \otimes \wedge^{n-1} T^{*} X$ and we can require (id $\otimes \perp$ ) $0 \widetilde{M}: J^{2 r-1} Y \rightarrow V^{*} Y \otimes S^{r-2} T X \otimes \Lambda^{n-2} T^{*} X$ to vanish. The coordinate
meaniner of this condition is $B_{p}^{j_{1} \cdots j_{2}} 2^{i}=B_{i}^{j_{1}} h_{2}{ }^{i /}$ and such a $1 /$ will be sald 1 , be quasisymmetric. lor $r-2$ ( 7 ) implies that there is a untuce quasisymmetric $1 /$ satisfying $\delta \lambda=\mathscr{Z} . U+E$. Its coordinate expression is
(10)

$$
\left|\left(L_{p}^{\prime} \quad D_{j} L_{p}^{j i}\right) \mathrm{d} y^{\prime \prime}+I_{p}^{j i} \mathrm{~d} y_{j}^{\prime}\right| \approx \omega_{i}
$$

However, one camot continue in such a procedure. For $r$. $\therefore$ we deduced las direet evaluation that the condition $B_{p}^{i j}=B_{p}^{j i}$ depends on the coordinate sstem (an obstruction beine formed by the second partial derivatives of the transformat tion on the base manifold) , |10|. p. 207. |0|. p. 473.

Hence a natural problem is how to determine a mique $/ /$ by means of an additional structure. We shall show that it sufficies to dde a linear symmetric connection J on l . which is more economical than the pars of connections used in [4] and [1]. To clarify the basic idea of our construction. We first consi-
 a vetor bunde over d . In other words, $S$ is a linear morphism such that pos- id. where $p: T^{r}{ }^{1 *} X \rightarrow T^{*} X$ is the canonical projection. Then we shall show that every $\Gamma$ determines a splitting $\Gamma_{r}, \quad: T^{*} \lambda \rightarrow T^{r}{ }^{1 *} \neq \lambda$.

Given any vector bundle $E-X$. we define $E_{s}^{0}$ by an exact sequence.

$$
\begin{equation*}
0 \rightarrow E_{s}^{0} \rightarrow J^{s} E \rightarrow E \rightarrow 0 \tag{111}
\end{equation*}
$$

A canonical map $x: J^{s}{ }^{1} E \in T^{s} * X \rightarrow E_{s}^{0}$ can be constructed as follows, $|11|$. [7]. Having $H=j_{x}^{5}{ }^{1} \sigma \in J^{s-1} E$ and $F=j_{x}^{s} f \in T^{s *} X$. $f o$ is a section of $L$. Obviously $f(x)=0$ implies that $j_{x}^{s}\left(f(0)\right.$ depends on $H$ and $F$ only and $j_{x}^{s}(f \sigma) \equiv E_{8}^{\prime \prime}$. This gives a bilinear map from the Whitney sum $J^{s}{ }^{1} E \because T^{s *} A$ into $E_{s}^{0}$ inducing $x$.


(12) $\quad g_{a}^{p}=\sum_{\beta+\gamma=a} \frac{\alpha!}{\beta!\gamma!} h_{\beta}^{p} a_{\gamma}$
where the sum is taken over all multiindicial decompositions of $\alpha$. If we add a splitting $S: T^{*} X \rightarrow T^{s *} X, a_{\gamma}=S_{\gamma}^{i} a_{i} . S_{j}^{i}=\delta_{j}^{i}$, we obtain a map $\chi o(\mathrm{id} \otimes S): I^{s-1} E \sigma$ $T^{*} X \rightarrow E_{s}^{0}$ with the following coordinate expression

$$
\begin{equation*}
g_{a}^{p}=\sum_{\gamma+\gamma=\alpha} \frac{\alpha!}{\beta!\gamma!} S_{\gamma}^{i} h_{\beta}^{p} a_{i} \tag{13}
\end{equation*}
$$

Given a fibred manifold $Y$, one analogously introduces a map

$$
x:\left(\begin{array}{ll}
\pi_{s}^{s} & 1 \tag{14}
\end{array}\right)^{\prime} V J^{s-1} Y \otimes T^{s * X} \rightarrow V J^{s} Y
$$

by means of the canonical identification $V J^{s} Y \approx J^{s} V Y$, [5]. Every $G \in V J^{s} Y$ corresponds to an $s$-jet $j_{x}^{s} \sigma$, where $\sigma$ is a local section of $V Y \rightarrow X$. Then $j_{x}^{s}(f \sigma)$ is identified with an element of $K_{s}^{0}$. This induces $x$ by bilinearity. If we add a splitting $S: T^{*} X \rightarrow T^{s *} X$, then (13) implies that the coordinate expression of $\widetilde{S}=x o(\mathrm{id} \otimes S):\left(\pi_{s}^{s-1}\right)!V J^{s-1} Y \otimes T^{*} X \rightarrow V J^{s} Y$ is

$$
\begin{equation*}
\mathrm{d} y_{\alpha}^{p}=\sum_{\beta+\gamma=a} \frac{\alpha!}{\beta!\gamma!} S_{\gamma}^{i} \mathrm{~d} y_{\beta}^{p} \otimes \partial_{i} \tag{15}
\end{equation*}
$$

Every linear symmetric connection $\Gamma$ on $X$ determines a splitting $\Gamma_{s}: T^{*} X \rightarrow$ $T^{s *} X$ as follows. Every $a \in T_{x}^{*} X$ can be interpreted as a linear map $\lambda(a): T_{x} X \rightarrow \mathbf{R}$. Consider the exponential map exp of $\Gamma$ restricted to a diffeomorphism from a neighbourhood $0 \in U \subset T_{x} M$ into a neighbourhood $x \in V \subset X$. Then $\lambda(a) \circ$ $\exp ^{-1}: V \rightarrow \mathbf{R}$ and we define $\Gamma_{s}(a)=j_{x}^{s}\left(\lambda(a) \circ \exp ^{-1}\right)$.

Given a splitting $S: T^{*} X \rightarrow T^{r-1 *} X$, a morphism $M: J^{2 r-1} Y \rightarrow V^{*} J^{r-1} Y \otimes$ $\Lambda^{n-1} T^{*} X$ will be called $S$-quasisymmetric, if the resulting map in the following diagram vanishes


In particular, if $\Gamma$ is an integrable connection and $x^{i}$ is an affine local coordinate system of $\Gamma$, then $\Gamma_{r-1}$ is determined by $S_{\beta}^{i}=0,|\beta| \geqslant 2$. Then one finds easily that $M$ is $\Gamma_{r-1}$-quasisymmetric if and only if

$$
\begin{equation*}
B_{p}^{j_{1} \cdots j_{s} j i}=B_{p}^{j_{1} \cdots j_{s} i j} \quad \text { for all } s \tag{17}
\end{equation*}
$$

This is a justification of our terminology.
PROPOSITION 1. For every splitting $S: T^{*} X \rightarrow T^{r-1} * X$ there exists a unique $S$-quastsymmetric morphism $M_{S}: J^{2 r-1} Y \rightarrow V^{*} J^{r-1} Y \otimes \wedge^{n-1} T \quad X$ satisfying $\delta \lambda=\mathscr{D} M_{S}+E$.

Proof. Take a local coordinate system $x^{i}$ on $X$ and consider first the local splitting determined by the integrable comnection corresponding to $x^{i}$. Then the
symmetries (17) imply that all $B$ 's in (7) are uniquely determined and
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$$
\begin{aligned}
B_{p}^{j_{1} \cdots j_{k} i} & =L_{p}^{j_{1} \cdots j_{h} i}-D_{1} L^{\left(j_{1} \cdots j_{k} i\right.}+\ldots \\
& \left.+(-1)^{s}\right)_{1} \ldots l_{p}^{1} l_{s} j_{1} j_{k}
\end{aligned}
$$

with $s+h+1=r$. For an arbitrary splitting $S$. we deduce by $(15) B_{p}^{j_{1} / h_{h} / i}$. $B_{p}^{j_{1} i_{k} i l}+$ certain linear combinations of the products of $B^{\prime} s$ with more superseripts with some $S$ s. Then (7) gives
(19)

$$
B_{p}^{j_{1} \cdots j_{k}}=I_{p}^{j_{1} \cdots j_{k}}-D_{i} B_{p}^{j_{1} \cdots j_{k}{ }^{i}}+C_{p}^{j_{1} \cdots j_{h}}
$$

where $\left({ }_{p}^{j_{1} \cdots i_{k}}\right.$ is a certain linear combination with rational cocfifients of the products $B_{p}^{i_{1} \ldots i_{k}} 2^{i}{ }^{1} \ldots s^{i} S_{i_{1}}^{j} \ldots i_{s}$ (no summation), $s \geqslant 2$. This determines $1_{s}$.

The morphism $H_{S}$ will be called the Poincare-Cartan morphism of $\lambda$ determin ed by $S$. For $S=\left[\right.$, we say that $M_{r_{r}}=H_{1}$ is determined hy $I$. Since the global existence of a linear symmetric connection on every $X$ is a well-known fact. Proposition 1 gives another proof of the global existence of the Poincare Cartan morphisms.

For $r=2$ one can take the identity map of $T^{*} \lambda$ only, which gives (10) For $r=3$. any splitting $T^{*} X \rightarrow T^{2} * X$ coincides with a linear symmetric conncetion I on $X$. In general. local coordinates $x^{i}$ or $X$ induce the additional coordinates $f_{i_{1} \ldots i_{h}}=\partial_{i_{1}} \ldots \dot{\partial}_{i_{k}} f$ on $T^{s * \lambda} \hat{\lambda}, k=1 \ldots$. . If $f_{i j}=\Gamma_{i j}^{h} f_{h}$ are the equations. of $\Gamma$. then the coefficients of $M_{\Gamma}$ are

$$
\begin{align*}
& \left.B_{p}^{j k \backslash}=L_{p}^{j k} \cdot B_{p}^{j i}=L_{p}^{j i}-i\right)_{k} L_{p}^{j i k}+L_{p}^{k \cdot 1 j} \Gamma_{k:}{ }^{\prime!} .  \tag{20}\\
& B_{p}^{i}=L_{p}^{i}-D_{j} L_{p}^{j i}+D_{j k} L_{p}^{j k i}-D_{j} L_{p}^{k \times j \Gamma_{k}}{ }^{i!} .
\end{align*}
$$

We now describe an algorithm for finding the equations of the splitting $l^{\circ}$ : $T^{*} \mathrm{X} \rightarrow T^{s *} \mathrm{X}$ determined by $\mathrm{I}^{\prime}$ in an arbitrary local coordinate system on X (in the normal coordinate system of $I^{\circ}$ at $x \in A$, the equations of $\Gamma_{a}$ at $x$ are $f_{i j}=0 \ldots i_{i_{1} \ldots i_{s}}=0$ by definition). This is based on the fact that the second and higher order derivatives of $\lambda$ (a) oexp ${ }^{\text {1 }}$ along each geodesics passing through $x$ vanish. We find the explicit formulae for $\Gamma_{2}$ and $\Gamma_{3}$. The equations of geodesich are
(21)

$$
\frac{\mathrm{d}^{2} x^{i}}{\mathrm{~d} t^{2}}+\Gamma_{j k}^{i} \frac{\mathrm{~d} x^{j}}{\mathrm{~d} t} \frac{\mathrm{~d} x^{k}}{\mathrm{~d} t}=0
$$

and the second derivative of a function $f$ along a curve $x^{i}(f)$ is
(22)

$$
\frac{\partial^{2} f}{\partial x^{i} \partial x^{j}} \frac{\mathrm{~d} x^{i}}{\mathrm{~d} t} \frac{\mathrm{~d} x^{j}}{\mathrm{~d} t}+\frac{\partial f}{\partial x^{i}} \frac{\mathrm{~d}^{2} x^{i}}{\mathrm{~d} t^{2}}
$$

Hence $f_{i j}=\Gamma_{i j}^{k} f_{k}$. In the third order we have to evaluate $\frac{\mathrm{d}^{3} x^{i}}{\mathrm{~d} t^{3}}$ from (21) and differentiate once more (22). Then our condition gives

$$
\begin{equation*}
f_{i j k}=\left[\partial_{(k} \Gamma_{i j)}^{\ell}+\Gamma_{m(i}^{\ell} \Gamma_{j k)}^{m}\right] f_{\ell} . \tag{23}
\end{equation*}
$$

In this way, one can proceed step by step on.

## 2. REGULAR LAGRANGIANS

Our definition of a regular $r$-th order Lagrangian is motivated by Proposition 2 below and our requirements are stronger than in [2]. Our approach is inspired by Shadwick, [12], but we use a direct geometric construction applied to the Lagrangian itself (we remark that the results mentioned in §l imply that Shadwick's momenta are not geometrically well defined for $r>2$ and $n>1$ ).

If we restrict $\delta \lambda$ to $K_{r}^{r-1}$, we obtain a linear map $\Lambda(u): V Y \otimes S^{r} T^{*} X \rightarrow \wedge^{n} T^{*} X$, or an element $\Lambda(u) \in V^{*} Y \otimes S^{r} T X \otimes \wedge^{n} T^{*} X$, for every $u \in J^{r} Y$. The pullback $L_{r} Y=\left(\pi_{r-1}^{0}\right)^{!} V^{*} Y \otimes S^{r} T X \otimes \wedge^{n} \cdot T^{*} X$ over $J^{r-1} Y$ will be called the $r$-th Legendre bundle of $Y$ and $\Lambda: J^{r} Y \rightarrow L_{r} Y$ will be called the Legendre transformation of $\lambda$ (the first order case was studied in [8]). If we introduce fibre coordinates on $L_{r} Y$ by the decomposition $s_{p}^{j_{1} \ldots j_{r}} \mathrm{~d}_{1}, p \otimes\left(\frac{\partial}{\partial x^{j_{1}}} \ldots \circ \frac{\partial}{\partial x^{j_{r}}}\right) \otimes \omega$, then the coordinate expression of the Legendre transformation is $x^{i}=x^{i}, y_{\alpha}^{p}=y_{\alpha}^{p},|\alpha| \leqslant r-1$ and $s_{p}^{j_{1} \cdots j_{r}}=L_{p}^{j_{1} \cdots j_{r}}$. The vertical differential of $\Lambda$ (over $J^{r-1} Y$ ) $\delta \Lambda: K_{r}^{r-1} \rightarrow$ $L_{r} Y$ can be viewed as a map $\delta \Lambda: J^{r} Y \rightarrow V^{*} Y \otimes S^{r} T X \otimes V^{*} Y \otimes S^{r} T X \otimes \Lambda^{n} T^{*} X$. For every $1 \leqslant k \leqslant r$. consider the canonical map

$$
\begin{equation*}
s_{k}: S^{r} T X \otimes S^{r} T X \rightarrow\left(S^{2 r-k} T X\right) \otimes S^{k} T X \tag{24}
\end{equation*}
$$

Then the induced map $\delta_{k} \Lambda=\left(\mathrm{id} \otimes s_{k}\right) \circ \delta \Lambda$ can be interpreted as

$$
\begin{equation*}
\delta_{k} \Lambda: J^{r} Y \rightarrow \operatorname{Hom}\left(V Y \otimes S^{k} T^{*} X \otimes \wedge^{n} T X, V^{*} Y \otimes S^{2 r-k} T X\right) \tag{25}
\end{equation*}
$$

DEFINITION. A Lagrangian $\lambda$ will be called $k$-regular, if the linear map $\left(\delta_{k} \Lambda\right)(u): V Y \otimes S^{k} T^{*} X \otimes \wedge^{n} T X \rightarrow V^{*} Y \otimes S^{2 r-k} T X$ is a monomorphism for every $u \in J^{r} Y$. A Lagrangian is said to be regular if it is $k$-regular for every $1 \leqslant$ $k \leqslant r$.

For any $\alpha=i_{1}+\ldots+i_{r}$, we set
(20) $\quad L_{q p}^{j_{1} i_{r} j_{1} j_{r}}=\frac{a!}{r!} j_{q}^{a} L_{p}^{j_{1} \cdots j_{r}}$.
 resularity of $\lambda$ is equivalent to the following condition. If
(27)

$$
L_{q b}^{i_{1} \ldots i_{,} j_{1} \ldots j_{r}}=i_{1}, i_{r} j_{1}, i_{h}{ }^{W} i_{k}-1 \ldots j_{r}=0
$$

for every $\left.=i_{1} \ldots i_{r} j_{1} j_{k} \in I^{*}\right\rangle \sigma S^{2 r} T X$, then $w_{j_{k+1}, j_{i}}^{p}=0$ (learly. $\lambda$ is $r$ regular if and only if $\lambda$ is a local diffeomorphism.

Let $\left.\psi: T J^{r}\right\} \rightarrow \mid J^{r}{ }^{1} Y$ be the structure form of $\left.J^{r}\right\} . \psi=\frac{v_{r}, ~ w i l l}{\prime \prime} y^{\prime \prime}$ $\omega_{0}^{\prime \prime}=d_{a}^{p}-r_{0}^{p} \cdot d_{i}^{i},[3]$. [5]. For any splitting $S$, we define an exterior $n$. form $\psi \pi M_{S}$ on $J^{2 r}{ }^{2}$ by natural combination of the contraction with respect to $\| J^{r}{ }^{1} Y$ and alternation, $\psi \pi M_{S}=\stackrel{\text { U }}{ } h_{p^{a}}^{i} \omega_{a}^{p} \wedge \omega_{i} \cdot|6|$. If we interpret $\lambda$ as an exterior $n$-form on $J^{r} Y$, then $\theta_{S}=\lambda+\psi \pi, U_{S}$ is an exterior $n$-form on $J^{2 r-1} Y$, which will be called the Poincare-Cartan form of $\lambda$ determined by $S$ (or by $\Gamma$ in the case $S=\Gamma_{r}{ }_{1}$ ).

In general. a section $u: X \rightarrow J^{s} Y$ is said to be $k$-holonomic. $k \leqslant s$. if $\pi_{s}^{k} u==$ $j^{k}\left(\pi_{s}^{0} t\right)$.

PROPOSITION 2. Let $\lambda$ be a regular Lagrangian and $S$ an spliting. If a section $\|: X \rightarrow J^{2 r+1} Y$ satisfies

$$
\begin{equation*}
\left.u^{*}(\zeta\lrcorner \mathrm{d} \theta_{S}\right)=0 \tag{28}
\end{equation*}
$$

for erery $\pi_{2 r-1}^{r}{ }^{1}$-vertical vector field $\zeta$ on $J^{2 r}{ }^{1} Y^{\prime}$, then u is $r$-holonomic.
Proof. By (18) and (19). every $B_{p}^{I_{1} \cdots j_{k} i}$ is a affine map from the affine bundle $J^{r+s} Y \rightarrow J^{r+s-1} Y$ into reals, $k+1+s=r$, the linear part of which is

$$
\begin{equation*}
(-1)^{s} L_{q \rho}^{i_{1} \ldots i_{r} l_{1} \ldots v_{s} j_{1} \ldots j_{k} i_{1}, y_{i}^{q}, i_{r} y_{1} \ldots v_{s}} \tag{29}
\end{equation*}
$$

independently on $S$. (In other words, (29) is the highest order part of $B_{p}^{j_{1} \ldots j_{k} i_{i}}$ ). Let $u_{i_{1} \ldots i_{k}}^{p}$ be the coordinate functions of $u$. Set $u^{*}\left(\omega_{j_{1}, j_{h}}^{P} \wedge \omega_{i}\right)=l_{l_{1} \ldots i_{h}}^{\prime} \omega_{i}, s o$ that $\left\langle p_{j_{1} \ldots j_{k} i}^{p}=\partial_{i} u_{j_{1} \ldots j_{k}}^{p} \cdots u_{j_{1} \ldots j_{k}}^{p}\right.$. Consider first a $\pi_{2 r}^{2 r}$-vertical vector field $\zeta_{1}$. Then the equation $u^{*}\left(\zeta_{1} \downharpoonleft \mathrm{~d} \theta_{S}\right)=0$ reads

Since $\lambda$ is 1 -regular. (30) implies $L_{i}^{p}=0$, so that $\|$ is 1 -holonomic. Assume by induction that $\left.u^{*}\left(\zeta_{k}\right\lrcorner \mathrm{d} \theta_{S}\right)=0$ for every $\pi_{2 r}^{2 r}{\underset{1}{k}}^{1}$-vertical vector fiod $\zeta_{k}$ implies that $u$ is $k$-holonomic, i.e. $u^{*} \omega_{a}^{p}=0$ for all $|\alpha| \leqslant k-1$. By (29), the condition $\left.u^{*}\left(\zeta_{k+1}\right\lrcorner \mathrm{d} \theta_{s}\right)=0$ for a $\pi_{2 r}^{2 r} 1_{1}^{k}$-vertical vector field $\zeta_{k, 1}=$
$r+s \in \ddot{L i}_{1} \leqslant 2 r-1 \zeta_{a}^{p} \partial_{p}^{\alpha}$ reads

$$
\begin{equation*}
L_{q p}^{i_{1} \ldots i_{r} \ell_{1} \ldots \ell_{s} i_{1} \ldots j_{k} i^{i} \zeta_{i_{1} \ldots i_{r} \ell_{1} \ldots \ell_{s}}^{q} U_{j_{1} \ldots j_{k} i}^{p}=0 . . . . ~ . ~} \tag{31}
\end{equation*}
$$

Since $\lambda$ is $(k+1)$-regular, (31) implies $U_{\left(j_{1} \ldots j_{k} i\right)}^{p}=0$. We have $u_{j_{1} \ldots j_{k}}^{p}=\partial_{j_{1}} \ldots$ $\partial_{j_{k}} u^{p}$ by the induction hypothesis. Then $U p_{\left.j_{1} \ldots j_{k} i\right)}=0$ implies $u_{j_{1} \ldots j_{k} i}^{p}=\partial_{i} \partial_{j_{1}} \ldots$ $\partial_{j_{k}} u^{p}$. Hence $u$ is $(k+1)$-holonomic. In the last step of this procedure we obtain that $u$ is $r$-holonomic.
Q.E.D.

REMARK 1. For $n=1$ a stronger result holds: if $\lambda$ is a regular Lagrangian with the (unique) Poincaré-Cartan form $\theta$ and $\left.u^{*}(\zeta\lrcorner \mathrm{d} \theta\right)=0$ for every $\pi_{2 r-1}^{0}$-vertical vector field $\zeta$ on $J^{2 r-1} Y$, then $u$ is $(2 r-1)$-holonomic, [6].

## 3. A GEOMETRICAL FORM OF THE HIGHER ORDER HAMILTON FORMALISM

A section $s: X \rightarrow Y$ is said to be a critical section of $\lambda$ if $\left(j^{2 r} s\right)^{*} E=0$. (In coordinates, $\left(j^{2 r} S\right)^{*} \mathrm{e}_{p}=0, p=1, \ldots, m$, are the Euler equations).

PROPOSITION 3. For any Lagrangian $\lambda$ and any splitting $S$, if an $r$-holonomic section $u: X \rightarrow J^{2 r-1} Y$ satisfies $\left.u *(\zeta\lrcorner \mathrm{d} \theta_{S}\right)=0$ for every $\pi_{2 r-1}$-vertical vector field $\zeta$ on $J^{2 r-1} Y$, then $s=\pi_{2 r-1}^{0} u$ is a critical section of $\lambda$.

Proof. We have $\theta_{S}=\lambda+\sum_{|\alpha| \leqslant r-1} b_{p}^{\alpha i} \omega_{\alpha}^{p} \wedge \omega_{i}$, so that

$$
\begin{align*}
& \left.\zeta\lrcorner \mathrm{d} \theta_{S}=\zeta\right\lrcorner \mathrm{d} \lambda+  \tag{32}\\
& \left.\sum_{|\alpha| \leqslant r-1}\left[(\zeta\lrcorner \mathrm{d} b_{p}^{\alpha i}\right) \omega_{\alpha}^{p} \wedge \omega_{i}-\zeta_{\alpha}^{p} \mathrm{~d} b_{p}^{\alpha i} \wedge \omega_{i}-b_{p}^{\alpha i} \zeta_{\alpha+i}^{p} \omega\right] .
\end{align*}
$$

Since $u$ is $r$-holonomic, the second term on the right-hand side vanishes on $u$. Hence $\left.u^{*}(\zeta\lrcorner \mathrm{d} \theta_{S}\right)=0$ is equivalent to

$$
\begin{equation*}
\left(\left(j^{r} s\right)^{*} L_{p}^{j_{1} \cdots j_{k}}\right) \omega=u^{*}\left(\mathrm{~d} B_{p}^{j_{1} \cdots j_{k} i} \wedge \omega_{i}\right)+\left(u^{*} B_{p}^{\left(j_{1} \cdots j_{k}\right)}\right) \omega \tag{33}
\end{equation*}
$$

$k=0, \ldots, r-1$. For $k=r, B_{p}^{j_{1} \cdots j_{r}}=L_{p}^{j_{1} \ldots j_{r}}$ are some functions on $J^{r} Y$, so that

$$
\begin{equation*}
u * B_{p}^{j_{1} \cdots j_{k+1}}=\left(j^{2 r k-1} s\right)^{*} B_{p}^{j_{1} \cdots j_{k+1}} \tag{34}
\end{equation*}
$$

for $k+1=r$. Assume by induction that (34) holds for some $k+1$ and we prove that (34) holds for $k$ as well. Since $\mathrm{d}\left(\left(j^{2 r-k-1} s\right)^{*} B_{p}^{j_{1} \cdots j_{k+1}}\right)=\left(j^{2 r-1} s\right)^{*}$. $D B_{p}^{j_{1} \cdots j_{k}+1}$ by the definition of the formal exterior differential, we have $u^{*}\left(\mathrm{~d} B_{p}^{j_{1} \cdots j_{k} i} \wedge \omega_{i}\right)=\mathrm{d}\left(\left(j^{2 r-k-1} s\right)^{*} B_{p}^{j_{1} \cdots j_{k} i}\right) \wedge \omega_{i}=\left(j^{2 r-k} s\right)^{*} D B_{p}^{j_{1} \cdots j_{k} i} \wedge \omega_{i}$. But
 $B_{p}^{j_{1} i_{h}}$ differs from $B_{p}^{\left(j_{1} \ldots j_{h}\right)}$ by some linear combinations with coedicionts defined on $l^{\prime}$ of $B^{\prime} ;$ with more superscripts and some their formal derivatives. But all these quantities are defined on $J^{2 r} k l^{1} y^{\prime}$ and their values on $u$ comedic with their values on $j^{2 r \cdot k}{ }^{1} s$ by the induction hypothesis and by the definition of the formal derivative. Hence (34) holds for $k$ superscipts as well. Thus. by induction. (34) is true for all $B^{\prime} S$. By (33) and (34), $w(5 . j d \theta s)=0$ is reduced to

$$
\begin{align*}
& \left(j^{r} s\right)^{*} L_{p}=\left(j^{2 r} s\right)^{*} D_{i} B_{p}^{i} \\
& \left(j^{r} s\right)^{*} L_{p}^{j_{1} \cdots j_{k}}=\left(j^{2 r} k_{s}\right)^{*} D_{i} B_{p}^{j_{1} \cdots j_{k} i}+\left(j^{2 r} k_{s}\right)^{*} B_{p}^{\left(j_{1} i_{k}\right)} \tag{35}
\end{align*}
$$

$k=1 \ldots r-1 . \quad$ Using $B_{p}^{j_{1} \cdots j_{r}}=L_{p}^{j_{1} \cdots j_{r}}$ and the backward elimination, we deduce $\left(j^{2 r} S\right)^{*} e_{p}=0$.

REMARK 2. Proposition 5 of [6] implies that every critical section 5 satisfies $\left.\left(j^{2 r-1} S\right)^{*}(\zeta\lrcorner \mathrm{d} \theta_{S}\right)=0$ for any splitting $S$ and any $\pi_{2 r-1}$-vertical vector field $\zeta$ on $J^{2 r-1} Y$.

A geometrical version of the higher order Hamilton formalism can be now formulated as follows.

PROPOSITION 4. Let $\lambda$ be a regular $r$-th order Lagrangian on $Y \rightarrow \lambda$ and $S: T^{*} \lambda^{*}$ $\rightarrow T^{r-1} * X$ be any splitting. If a section $u: X \rightarrow J^{2 r-1} Y$ satisfies $u^{*}\left(\zeta \ldots \mathrm{~d} \theta_{S}\right)=0$. then $s=\pi_{2 r-1}^{0}$ u is a critical section of $\lambda$.

Proof. Since $\lambda$ is regular, $u$ is $r$ holonomic by Proposition 2. Then $s$ is critical by Proposition 3.
Q.E.D

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